

1. *Course number and name*
ENGR 201: Dynamics
2. *Credits and contact hours*
3 credit hours; three 50-minute lecture sessions/week, or two 1-hr-15-minute lecture sessions/week, depending on semester
3. *Instructor's or course coordinator's name*
Instructor: Kwok Siong Teh, Associate Professor of Mechanical Engineering
Course coordinator: Kwok Siong Teh, Associate Professor of Mechanical Engineering
4. *Text book, title, author, and year*
Hibbeler, R.C. *Engineering Mechanics: Dynamics*, 14th ed. Pearson, 2015
 - a. *other supplemental materials*
Meriam, J. L., *Engineering Mechanics: Dynamics*, 8th ed., Wiley, 2015.
5. *Specific course information*
 - a. *brief description of the content of the course (catalog description)*
Vector treatment of kinematics and kinetics of particles, systems of particles and rigid bodies. Methods of work, energy, impulse and momentum. Vibrations and time response. Applications to one- and two-dimensional engineering problems
 - b. *prerequisites or co-requisites*
ENGR 102: Statics
 - c. *indicate whether a required, elective, or selected elective course in the program*
Required for Civil Engineering; required for Mechanical Engineering
6. *Specific goals for the course*
 - a. *specific outcomes of instruction, ex. The student will be able to explain the significance of current research about a particular topic.*
 - Students will demonstrate a good understanding of the motion, velocity and acceleration of a point.
 - Students will demonstrate a good understanding of the difference between a curve and its parameterization.
 - Students will demonstrate a good understanding of the use of the instantaneous state to derive equations of motion.
 - Students will demonstrate a good understanding of the meaning of the terms in Newton's Laws of Motion, especially the second law $F= ma$.
 - Students will demonstrate a good understanding of the concepts of work, energy, and power.
 - Students will demonstrate a good understanding of conservative and non-conservative system.
 - Students will demonstrate a good understanding of the concept of angular velocity of a rigid body or reference frame.
 - Students will demonstrate a good understanding of time rates of change of unit vectors in a rotating reference frame.

- Students will demonstrate a good understanding of absolute and relative velocity and acceleration in a rotating reference frame.
- Students will demonstrate a good understanding of the computation of linear momentum and moment of a rigid body.
- Students will demonstrate a good understanding of the use of Euler's laws of motion for two-dimensional problems.
- Students will demonstrate a good understanding of the concept of frequency and period for simple harmonic motion.
- Students will demonstrate a good understanding of the governing equation for the simple harmonic oscillator.

b. explicitly indicate which of the student outcomes listed in Criterion 3 or any other outcomes are addressed by the course.

Course addresses ABET Student Outcome(s): a, c, e, g, h, i, j, k.

7. *Brief list of topics to be covered*

- Position vector and its derivatives – velocity and acceleration.
- Rectilinear motion.
- Curvilinear motion in Cartesian, normal-tangential, and cylindrical coordinate systems.
- Constrained motion.
- Newton's laws of motion, especially the second law $F = ma$.
- Work, energy, and conservation of energy.
- Power.
- Linear impulse and momentum.
- Angular impulse and momentum.
- Conservation of linear and angular momentums.
- Impact and collisions.
- Two-dimensional rigid body kinematics.
- Euler's laws of motion for rigid bodies.
- Energy methods in rigid body motion.
- Free vibration (with and without damping)
- Forced vibration (with and without damping)